

VIGILANT VISION: HARNESSING FACIAL ANALYSIS FOR ROAD SAFETY AGAINST DROWSY DRIVING

Srinivas K M, Vairachilai S,

School of Computing Science and Engineering, VIT Bhopal University, KotriKalan, Sehore, Madhya Pradesh 466114

Abstract—Drowsy driving poses a critical challenge in India, contributing significantly to road accidents and fatalities. This research explores a solution leveraging facial recognition technology, specifically the VGG Face 16 architecture, for drowsy driving detection. The study aims to develop a robust system capable of early identification of drowsiness cues in drivers, potentially preventing accidents. The proposed solution outlines the architecture, dataset description, preprocessing steps, and working model of the VGG16-based system. The study's working process involves model training, validation, and visualization of performance metrics. The study's methodology entails model training, performance metric visualization, and assessment. The trained model exhibits a notable accuracy of 97.35 percent during the training phase. Further evaluations and testing on unseen data are advised to validate the model's real-world effectiveness and generalization. This research seeks to contribute significantly to mitigating the impact of drowsy driving on road safety and public well-being in India.

Index Terms—Drowsy Driving, Facial Recognition, VGG Face Model, Driver Drowsiness Detection, Road Safety, Deep Learning

I. INTRODUCTION

Drowsy driving presents a grave and pervasive issue in India, with potentially devastating consequences, accounting for up to 40% of road accidents in the country. In 2021, India witnessed a tragic toll, with over 1.5 lakh lives lost in road accidents, leaving countless others injured. Drowsy driving is a significant contributor to this alarming death toll, with its causes deeply rooted in the complex fabric of Indian society. One of the primary perpetrators behind drowsy driving is sleep deprivation. According to a 2019 study conducted by the National Sleep Foundation, India boasts the unenviable distinction of having the highest rate of sleep deprivation worldwide, with over 60% of adults regularly reporting insufficient sleep. This chronic sleep deficit contributes to drowsiness behind the wheel, endangering lives on the road. Fatigue, resulting from the strenuous demands of long hours spent driving or working, is another perilous factor. India, as a rapidly growing economy, places heavy burdens on its workforce, with many individuals compelled to work extended hours to support their families. This, in turn, leads to fatigue, a particularly critical concern among commercial drivers, such as truckers, who traverse vast distances and endure demanding schedules. Alcohol consumption further exacerbates the problem of drowsy driving. The high preva- lence of alcohol use in India not only impairs judgment and coordination but also induces drowsiness, making it a potent



Fig. 1: Drowsy Driver

factor in road accidents. The perilous practice of drinking and driving, fuelled by this culture of alcohol consumption, compounds the risks on the nation's roads. Additional factors contributing to drowsy driving in India encompass certain medications, medical conditions like sleep apnea, and circa- dian rhythm disorders, creating a multifaceted challenge that requires comprehensive attention. The consequences of drowsy driving in India are profound and far-reaching. It leads to a grim trail of serious injuries and death, both for the drivers themselves and for other road users. A 2018 study by the World Health Organization underscored the gravity of drowsy driving as a major cause of road accidents in India, further highlighting its significant contribution to the country's high fatality rate. Beyond the human toll, drowsy driving exacts a heavy economic toll. The costs associated with medical care, vehicle repairs, and lost productivity place a substantial burden on the Indian economy. A 2017 study by the Indian Chamber of Commerce and Industry estimated that the annual economic cost of road accidents in India exceeds INR 10 lakh crore, underscoring the need for effective measures to combat drowsy driving. Reduced productivity is yet another facet of this issue, as drowsy drivers are more prone to making errors. The consequences ripple through society, affecting businesses and the economy at large, as mistakes and accidents result in lost productivity and resources. In sum, drowsy driving is a multifaceted crisis deeply entrenched in Indian society, demanding comprehensive solutions to mitigate its profound impact on lives, the economy, and the overall well-being of the nation. To overcome this, Facial recognition technology offers a promising new approach to drowsy driving detection. It is non-invasive, can be used in any lighting condition, is more sensitive, and can detect drowsiness earlier. The VGG Face model is a deep learning model that has been trained on a massive data set of facial images. It can extract intricate facial features and patterns, which can be used to identify subtle hints of drowsiness, such as drooping eyelids, yawning, and difficulty focusing. This research aims to develop a robust drowsy driving detection system that relies on facial behaviour analysis using the VGG Face model. This system will provide early warnings to drivers who exhibit signs of sleepiness, allowing them to take corrective actions or rest before a po- tential accident occurs. Additionally, this technology could be integrated into advanced driverassistance system (ADAS) and autonomous vehicles to further enhance their safety features and prevent accidents caused by drowsy driving. This research has the potential to make a significant contribution to the field of drowsy driving detection and road safety. By developing a highly effective, non-invasive, and real-time solution for detecting sleepiness in drivers, it can help save lives and reduce accidents.

II. LITERATURE SURVEY

This article offers a look, at the improvements in detecting driver fatigue. It discusses methods such as learning and analyzing eye movements emphasizing their impact on ensur- ing road safety. Recent research demonstrates advancements in recognizing drowsiness and reducing accidents linked to tired driving. Future studies ought to focus on overcom- ing challenges and incorporating strategies to improve the performance of drowsiness detection systems. In summary the results emphasize the significance of progress, in this aspect of transportation safety. Rateb Jabbara et al (2018) used a multilayer perceptron classifier to identify the driver's state based on facial landmark data. Their system achieved an accuracy of 81% and was indicated to be integrated into advanced driver-assistance systems, driver drowsiness detection systems, and mobile applications. The authors also mentioned that future work would focus on detecting driver distraction and yawning [1]. Bhargava Reddy et al (2019) designed and compressed a deep learning model specifically for driver drowsiness detection on embedded systems. Their model utilized minimal facial landmarks and employed a knowledge distillation technique to achieve high accuracy and real-time performance. The study's results suggested that the eyes and mouth played crucial roles in classifying drowsiness [2]. Israt Jahan et al (2023) proposed a lightweight deep- learning model for drowsiness detection on embedded systems. The model classifies eye states to detect drowsiness and achieves high accuracy (95.93%-97.50%) on three networks: VGG16, VGG19, and 4D. The model outperforms similar drowsiness detection methods, making it a promising solution for embedded systems [3]. Wanghua Deng and Ruoxue Wu (2019) have discussed that DriCare is a novel real-time system for evaluating driver fatigue based on face tracking and facial key point detection. It uses a new MC-KCF algorithm to track the driver's face and introduces a new evaluation method for drowsiness based on the states of the eyes and mouth [4]. Esra Civik et al (2023) have proposed driver fatigue detection system achieves high accuracy (93.6% and 94.5% for eye and mouth models, respectively) and real-time performance (22 fps on a computer and 6 fps on a Nvidia Jetson Nano embedded device). It is more successful in detecting fatigue and yawning of drivers than other methods, but it has some limitations, such as requiring good lighting conditions and only detecting fatigue based on facial and eye regions [5]. According to a study conducted by Ratnesh Kumar Shukla and colleagues (2023) they have put forward a solution to address the rising risk of traffic accidents caused by drivers who're drowsy, due to the increasing number of vehicles on the road. The study explores approaches, such as using learning techniques based on EEG and CNN for detecting drowsiness as well as introduc- ing a unique method that considers individual characteristics in detecting sleepiness. The proposed model, which combines MTCNN, SVM and EAR analysis demonstrates performance compared to existing models, in monitoring and preventing accidents related to drowsiness [6]. Lisheng Jin et al (2013) developed 13 sleepiness detection models using four eye movement variables, including blink frequency, PERCLOS, gaze direction, and fixation time. The models showed high accuracy (72.23% for the general model and even higher for specific models), especially for detecting drowsy drivers. Individual differences are important when building detection algorithms. More features and realworld driving data should be considered in future studies [7]. H. Varun Chand and J. Karthikeyan (2022) detected driver drowsiness systems and aim to reduce accidents, but longer distraction detection delays hinder progress. Their study proposes a two-level CNN model to swiftly classify driver behaviour and emotion, achieving a 93% accuracy, which can greatly reduce accidents and save lives in the future [8]. Keyong Li et al (2015) proposed a driving style classification method to detect driver sleepiness. The findings indicate that the optimal performance is achieved when using SVM models, for drivers. However it is impractical to establish a model for each driver. The authors propose a strategy of developing models, for different categories based on driving styles [9]. Vijay Kumar and his team (2022) utilized a classifier called a perceptron to analyze landmark data and determine the state of the driver. The results were quite remarkable, with an accuracy rate of 81%. This finding suggests that the technology has promising applications, in driver assistance systems, drowsiness detection systems and even mobile applications. Moving forward the authors expressed their intention to expand their research to encompass identifying driver distraction and yawning in studies [10].

III. DATASET DESCRIPTION

The data set Collected from Prasad V Patil (Drowsiness Detection Data set), Ismail Nasri (Driver Drowsiness Data set (DDD) are in Kaggle. The Driver Drowsiness Data set (DDD) is an extracted and cropped faces of drivers from the videos of the Real-Life Drowsiness Data set. The frames were extracted from videos as images using VLC software. After that, the Viola-Jones algorithm has been used to extract the region of interest from captured images. The obtained data set (DDD) has been used for training and testing CNN architecture for driver drowsiness detection.

A. Contribution

The main finding of this research paper is mentioned below

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Fig. 2: Open Eye Data



Fig. 3: Closed Eye Data

- B. Data Cleaning and Preprocessing
- The process initiates by loading the image files.
- The main task of data cleaning involves categorizing the images into two categories.
- These preprocessing tasks can be achieved by using the Keras.preprocessing module.
- C. Data Integration of Advanced Neural Networks

• This research contributes to the field of image generation with CNN to analyze and interpret image content.

• This integration enhances the capability to generate out- put based on image content.

D. Data Model Evaluation

• The Model has greatly helped in classifying images due to its straightforward design.

• By using small filters and ReLU activation, it efficiently extracts features. However, its depth makes it computa- tionally demanding for evaluating models.

IV. PROPOSED SOLUTION

A. Introduction to Architecture

VGG16, short for Visual Geometry Group 16, is a widely used deep convolutional neural network (CNN) architecture designed primarily for image classification. This neural net- work has 16 layers, including 13 convolutional layers and 3 full layers. VGG16's processing engine starts from the input image and goes through the convolutional process. These layers use tiny filters to detect key features like edges, textures, and patterns. The Rectified Linear Unit (ReLU) function,

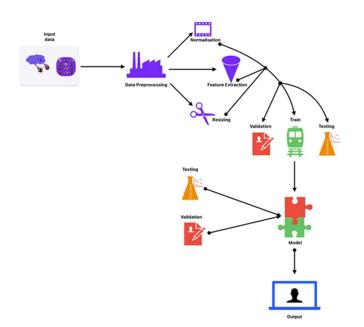


Fig. 4: Proposed Solution

which expresses inequality, plays an important role. VGG16 includes a maximum pooling layer that reduces the spatial di- mension to overcome computational complexity and preserve important features. The layers gradually deepen, allowing the network to learn more advanced features. After the convolution process, VGG16 performs classification over three layers by integrating high-level features. Usually, the last layer uses the SoftMax staging function to create useful classes. VGG16's simple and integrated architecture makes it easy to use and understand. However, its depth requires significant computing resources, making it less useful in existing applications where more efficient methods such as ResNet or Inception are available

B. Dataset and Preprocessing

Preprocessing a data set to detect drowsiness factors in- volves several key steps. First, collect video or images of the driver's face and eyes. We then extract frames containing faces and eyes. These images are then resized and normalized to ensure consistency. Apply a face detection algorithm to separate the face and eye region of interest. Perform image enhancement, including contrast and brightness adjustments, to improve the quality of the eye images. Additionally, apply techniques like histogram equalization to reduce lighting varia- tions. Finally, label the data, categorizing frames as "drowsy" or "non-drowsy" to create a labelled data set for training a machine learning model. Proper preprocessing enhances model accuracy and robustness in detecting drowsy drivers.

C. Working model

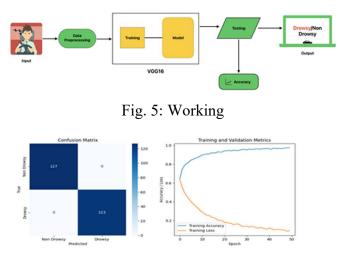


Fig. 6: Result

From Fig [5] the inputted data get processed then it goes to the next stage for data preprocessing the data gets cleaned and moves to the model stage this data gets trained with the sample data and it uses VGG Face 16 Architecture and after the training, the data gets trained. It moves to the next stage known testing phase in this stage gets trained and validated with the training data set and it moves to the next phase to show the expected output.

V. WORKING

Starting with the loading of a trained VGG16 model the code adjusts it specifically for detecting drowsiness. Initially, the top layers are frozen allowing only the added layers to undergo training. To make the model more robust data augmentation is strategically applied to the training set.

The training process takes place over a number of epochs updating weights based on training data. After that, the model is evaluated using a validation set providing performance met-rics that are then printed. An essential part of this evaluation is generating a confusion matrix that shows how accurately the model classifies drowsy and drowsy states. In order to visually explore the model's learning journey, the code concludes by visualizing the confusion matrix. At the time training and validation accuracy and loss are graphically represented over epochs. This dual visualization offers insights, into how the model learns and performs overall. Once this rigorous training and evaluation process is complete the model is saved in a designated file, for use.

It's crucial to emphasize that the effectiveness of this model depends on having quality and representative training data. Furthermore, the code understands the importance of adjusting hyper parameters and making refinements to enhance the model's effectiveness, in real-world situations. This ac- knowledgment emphasizes a dedication, to improvement and adaptation in order to achieve the outcomes in practical use cases.

VI. RESULTS

With the 41,793 images in the data set and training process for the neural network a final training accuracy of 97.35% with a loss of 0.0821. During validation, the model demon-strated robust

performance, reaching 100% accuracy with a minimal loss of 0.0013. The training progress indicates rapid convergence, and the validation results affirm the model's effectiveness. Further analysis, such as testing on unseen data and assessing generalization, would be beneficial to ensure the model's real-world applicability.

VII. CONCLUSION

This paper focuses on drowsy driving peril in India employ- ing VGG face 16 model as a facial recognition technology. During validation of the trained system, as indicated above, a mean accuracy of 97.35% was recorded hence, proving its capacity to detect drowsy cues as early as possible. This study includes an elaborate design, datasets description and preprocessing stages useful as foundations for mitigating against drowsy driving accident. Further testing on unseen data will evaluate the model's real world applicability and generalizability. It would help a lot on enhancing road safety in India.

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VIII. BIOGRAPHY SECTION

Srinivas K M M.tech 1st Year student in the Department of (Artificial Intelligence and Data Science), School of Com- puting Science and Engineering at VIT Bhopal University.

Vairachilai.S.Dr Working as a Senior Assistant Professor and Program Chair of Integrated M.Tech. CSE (Computational and Data Science), School of Computing Science and Engi-neering, VIT Bhopal University.